

THE Z-TRANSFORM

Fundamentals of the Z-Transform

The z-transform simplifies the analysis of linear time-invariant discrete-time (LTID) systems. It converts equations with integrals and derivatives into algebraic equations. The z-transform method of analyzing discrete-time systems is comparable to the Laplace transform method of analyzing continuous-time systems.

THE UNILATERAL Z-TRANSFORM

The unilateral z-transform is capable of analyzing only causal systems with causal inputs (signals starting at $k = 0$).

$$F[z] \equiv \sum_{k=0}^{\infty} f[k]z^{-k}$$

where:
 $F[z]$ is the *z*-transform
 z is complex in general
 $f[k]$ is a discrete-time signal

THE INVERSE Z-TRANSFORM

$$f[k] = \frac{1}{2\pi j} \oint F[z]z^{k-1} dz$$

where:
 \oint indicates integration around a circular path in the complex plane centered at the origin
 $F[z]$ is the *z*-transform
 z is complex in general
 $f[k]$ is a discrete-time signal

THE BILATERAL Z-TRANSFORM

The bilateral z-transform is capable of analyzing both causal and non-causal systems.

$$F[z] \equiv \sum_{k=-\infty}^{\infty} f[k]z^{-k}$$

It is helpful when working these problems to know that: $1 + x + x^2 + x^3 + \dots + x^{\infty} = \frac{1}{1 - x}$

A TABLE OF Z-TRANSFORMS

	$f[k]$	$F[z]$
1	$\delta[k - j]$	z^{-j}
2	$u[k]$	$\frac{z}{z-1}$
3	$ku[k]$	$\frac{z}{(z-1)^2}$
4	$k^2 u[k]$	$\frac{z(z+1)}{(z-1)^3}$
5	$k^3 u[k]$	$\frac{z(z^2 + 4x + 1)}{(z-1)^4}$
6	$\gamma^{k-1} u[k-1]$	$\frac{1}{z-\gamma}$
7	$\gamma^k u[k]$	$\frac{z}{z-\gamma}$
8	$k\gamma^k u[k]$	$\frac{\gamma z}{(z-\gamma)^2}$
9	$k^2 \gamma^k u[k]$	$\frac{\gamma z(z+\gamma)}{(z-\gamma)^3}$
10	$\frac{k(k-1)(k-2)\cdots(k-m+1)}{\gamma^m m!} \gamma^k u[k]$	$\frac{z}{(z-\gamma)^{m+1}}$
11a	$ \gamma ^k \cos \beta k u[k]$	$\frac{z(z - \gamma \cos \beta)}{z^2 - (2 \gamma \cos \beta)z + \gamma ^2}$
11b	$ \gamma ^k \sin \beta k u[k]$	$\frac{z \gamma \sin \beta}{z^2 - (2 \gamma \cos \beta)z + \gamma ^2}$
12a	$r \gamma ^k \cos(\beta k + \theta) u[k]$	$\frac{rz[z \cos \theta - \gamma \cos(\beta - \theta)]}{z^2 - (2 \gamma \cos \beta)z + \gamma ^2}$
12b	$r \gamma ^k \cos(\beta k + \theta) u[k]$	$\frac{(0.5re^{j\theta})z}{z-\gamma} + \frac{(0.5re^{-j\theta})z}{z-\gamma^*}, \quad \gamma = \gamma e^{j\beta}$
12c	$r \gamma ^k \cos(\beta k + \theta) u[k]$	$\frac{z(Az + B)}{z^2 + 2az + \gamma ^2}$
$r = \sqrt{\frac{A^2 \gamma ^2 + B^2 - 2AaB}{ \gamma ^2 - a^2}}$ $\beta = \cos^{-1} \frac{-a}{ \gamma }, \quad \theta = \tan^{-1} \frac{Aa - B}{A\sqrt{ \gamma ^2 - a^2}}$		

A TABLE OF Z-TRANSFORM OPERATIONS

Operation	$f[k]$	$F[z]$
Addition	$f_1[k] + f_2[k]$	$F_1[z] + F_2[z]$
Scalar multiplication	$af[k]$	$aF[z]$
Right-shift	$f[k-m]u[k-m]$	$\frac{1}{z^m} F[z]$
	$f[k-m]u[k]$	$\frac{1}{z^m} F[z] + \frac{1}{z^m} \sum_{k=1}^m f[-k]z^k$
	$f[k-1]u[k]$	$\frac{1}{z} F[z] + f[-1]$
	$f[k-2]u[k]$	$\frac{1}{z^2} F[z] + \frac{1}{z} f[-1] + f[-2]$
Left-shift	$f[k+m]u[k]$	$z^m F[z] - z^m \sum_{k=0}^{m-1} f[k]z^{-k}$
	$f[k+1]u[k]$	$zF[z] - zf[0]$
	$f[k+2]u[k]$	$z^2 F[z] - z^2 f[0] - zf[1]$
	$f[k+3]u[k]$	$z^3 F[z] - z^3 f[0] - z^2 f[1] - zf[2]$
Multiplication by γ^k	$\gamma^k f[k]u[k]$	$F\left[\frac{z}{\gamma}\right]$
Multiplication by k	$k f[k]u[k]$	$-z \frac{d}{dz} F[z]$
Convolution	$f_1[k] * f_2[k]$	$F_1[z]F_2[z]$
Initial value	$f[0]$	$\lim_{s \rightarrow \infty} F[z]$
Final value	$\lim_{N \rightarrow \infty} F[N]$	$\lim_{z \rightarrow 1} (z-1)F[z],$ poles of $(z-1)F[z]$ inside the unit circle